

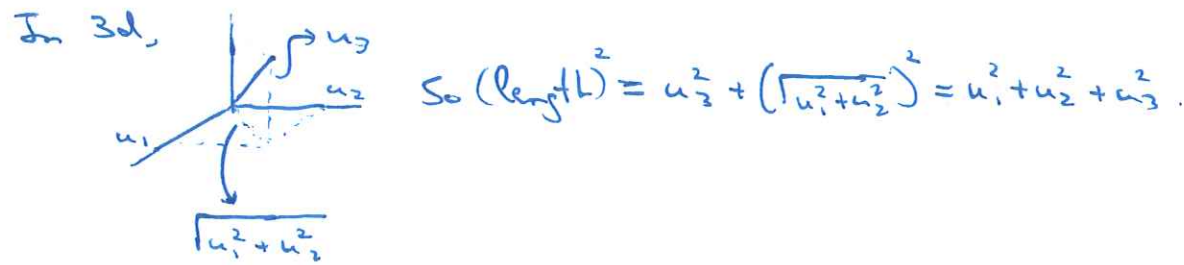
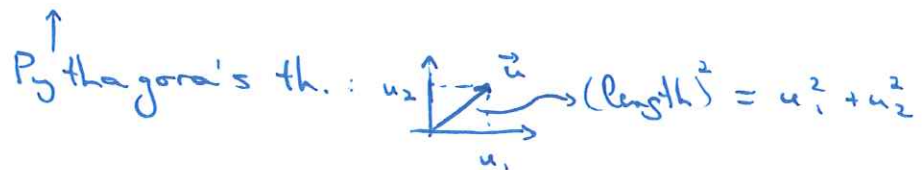
MATH 312
LECTURE 11

: Orthogonality and Projections.

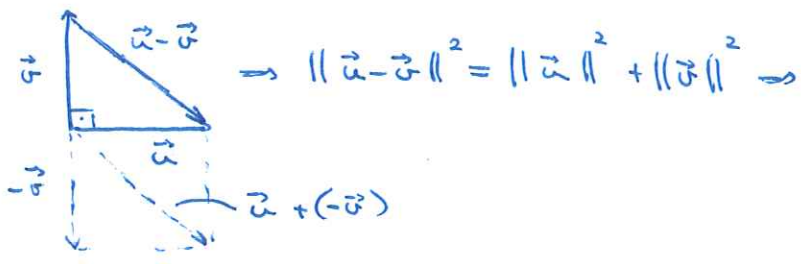
(Review/finish matrix of lin. transf.) (pages -85- to -89-).

I. Orthogonal complements

length of a vector: $\|\vec{u}\| = (u_1^2 + u_2^2 + \dots + u_n^2)^{1/2} = (\vec{u} \cdot \vec{u})^{1/2} = (\vec{u}^T \vec{u})^{1/2}$



Orthogonal vectors:



$$\begin{aligned} &\rightarrow \underbrace{u_1^2 + \dots + u_n^2 + v_1^2 + \dots + v_n^2}_{\|\vec{u}\|^2 + \|\vec{v}\|^2} = \underbrace{(u_1 - v_1)^2 + \dots + (u_n - v_n)^2}_{\|\vec{u} - \vec{v}\|^2} = \\ &= u_1^2 + v_1^2 - 2u_1v_1 + \dots + u_n^2 + v_n^2 - 2u_nv_n \end{aligned} \quad \left. \vphantom{\begin{aligned} &\rightarrow \dots \\ &= \dots \end{aligned}} \right\} \rightarrow$$

$$\Rightarrow -2u_1v_1 - 2u_2v_2 - \dots - 2u_nv_n = 0, \text{ i.e., } \vec{u} \cdot \vec{v} = 0!$$

|| So, two vectors \vec{u}, \vec{v} are orthogonal (or perpendicular) if and only if $\vec{u} \cdot \vec{v} = 0$.

• Remark: Recall that $\vec{u} \cdot \vec{v} = \vec{u}^T \vec{v} = \vec{v}^T \vec{u}$

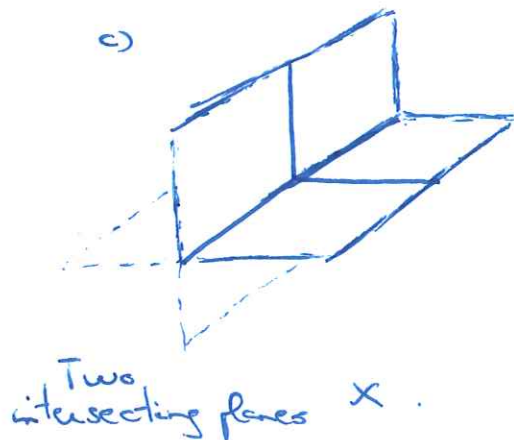
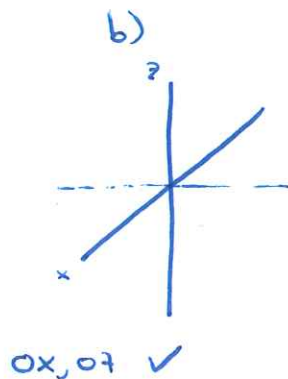
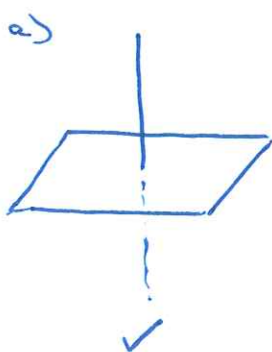
$$[u_1 \ u_2 \ \dots \ u_n] \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = u_1v_1 + u_2v_2 + \dots + u_nv_n.$$

• Remark: The zero vector, $\vec{0}$, is orthogonal to any vector.

• Def: Two subspaces U and V of \mathbb{R}^n are orthogonal if every vector $\vec{u} \in U$ is orthogonal to every vector $\vec{v} \in V$, i.e.,

$$U \perp V \text{ if } \forall \vec{u} \in U, \forall \vec{v} \in V, \text{ then } \vec{u} \cdot \vec{v} = 0.$$

Examples:



• Def: Orthogonal complement

Let V be a subspace of \mathbb{R}^n . Then, the collection of all vectors orthogonal to V is also a subspace of \mathbb{R}^n , denoted by V^\perp (and called "the orthogonal complement" of V).

Examples: a) \checkmark , b) \times , c) \times

\downarrow
they are orthogonal, but they don't "fill" \mathbb{R}^n .

→ The definition requires:

1) V and V^\perp are orthogonal ($\forall \vec{a} \in V, \vec{b} \in V^\perp, \vec{a} \cdot \vec{b} = 0$).

2) $\dim V + \dim V^\perp = n$ ($V, V^\perp \subseteq \mathbb{R}^n$)

• Fundamental Theorem of Linear Algebra

Let A be an $m \times n$ matrix. Then,

- 1) $N(A)$ and $C(A^T)$ are subspaces of \mathbb{R}^n ,
 2) $N(A^T)$ and $C(A)$ are subspaces of \mathbb{R}^m ,
- $\dim N(A) + \dim C(A^T) = n$,
 $\dim N(A^T) + \dim C(A) = m$,
 $\dim C(A) = \dim C(A^T) = \text{rank}(A)$.
- ← (we knew all this) and

$$\left\| \begin{aligned} N(A) &= C(A^T)^\perp \\ C(A) &= N(A^T)^\perp \end{aligned} \right\|$$

• Let's see why the second part is true:

1) $N(A) = C(A^T)^\perp$:

$N(A) = \{ \vec{x} \in \mathbb{R}^n : A\vec{x} = \vec{0} \}$, $C(A^T) = \text{span} \{ \text{rows of } A \}$.

So, if $\vec{x} \in N(A)$, then

$A\vec{x} = \vec{0} \sim \begin{bmatrix} \text{row 1} \\ \vdots \\ \text{row } m \end{bmatrix} \begin{bmatrix} \vec{x} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$, that is,

$\left. \begin{aligned} (\text{row 1}) \cdot \vec{x} &= 0 \\ \vdots \\ (\text{row } m) \cdot \vec{x} &= 0 \end{aligned} \right\} \Rightarrow \vec{x} \text{ is orthogonal to } \underline{\underline{\text{all}}} \text{ rows of } A,$

therefore, \vec{x} is orthogonal to all vectors in $C(A^T)$, as they can be written as linear combinations of the rows:

$$\vec{b} \in C(A^T) \rightarrow \vec{b} = \alpha_1(\text{row } 1) + \dots + \alpha_m(\text{row } m) \rightarrow$$

$$\Rightarrow \vec{x} \cdot \vec{b} = \alpha_1 \underbrace{\vec{x} \cdot (\text{row } 1)}_{=0} + \dots + \alpha_m \underbrace{\vec{x} \cdot (\text{row } m)}_{=0} = 0 //$$

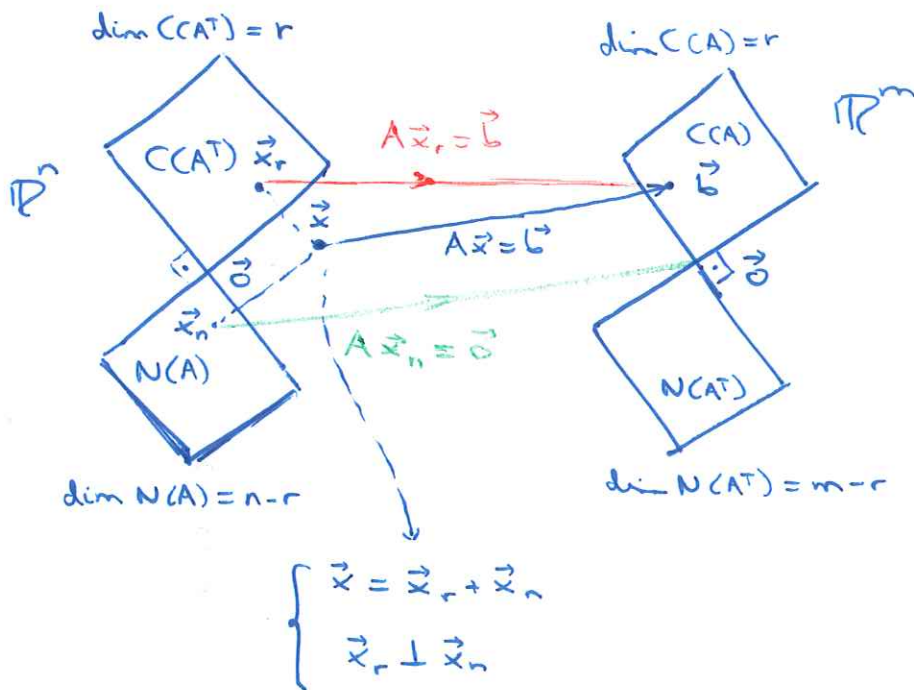
Finally, we know that $\dim N(A) + \dim C(A^T) = n$.

That is,

$$\left. \begin{array}{l} N(A) \perp C(A^T) \\ \dim N(A) + \dim C(A^T) = n \end{array} \right\} \Rightarrow N(A) \text{ and } C(A^T) \text{ are orthogonal complements. //$$

$C(A) = N(A^T)^\perp$ \rightarrow Do at home as an exercise //

Full picture



• Given any $\vec{x} \in \mathbb{R}^n$, we can decompose it as

$$\vec{x} = \vec{x}_r + \vec{x}_n \quad \text{with} \quad \vec{x}_r \cdot \vec{x}_n = 0.$$

$$\underbrace{\vec{x}_r}_{\in C(AT)} \quad \underbrace{\vec{x}_n}_{\in N(A)}$$

→ Remark: Given $\vec{b} \in C(A)$, there might be many $\vec{x} \in \mathbb{R}^n$ such that $A\vec{x} = \vec{b}$.

However, there is only one $\vec{x} \in C(AT)$ such that $A\vec{x} = \vec{b}$.

That is, all the $\vec{x} \in \mathbb{R}^n$ such that

$$A\vec{x} = \vec{b}, \text{ are of the form } \vec{x} = \underbrace{\vec{x}_r}_{\in C(AT)} + \text{"anything in } N(A)\text{"}$$

→ This can be used to define an "inverse" from $C(A)$ to $C(AT)$.
 ↙ pseudoinverse.